

## Atmospheric Dynamics

Lecture 10

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### **Fourier Series**

Each wave package (disturbance) can be represented as a sum of waves.





### **Fourier Series**

The representation of a perturbation as a simple sinusoidal wave might seem an oversimplification, since disturbances in the atmosphere are never purely sinusoidal.

It can be shown, however, that any reasonably well-behaved function of longitude can be represented in terms of a zonal mean plus a Fourier series of sinusoidal components:  $\infty$ 

$$f(x) = \sum_{s=1}^{\infty} (A_s \sin k_s x + B_s \cos k_s x)$$

 $k_s = \frac{2\pi s}{I}$  The zonal wave number (m<sup>-1</sup>)

L is the distance around a latitude circle,

s, the planetary wave number, is an integer des designating the number of waves around a latitude circle.



# **Fourier Series**



disturbance



The coefficients  $A_s$  are calculated by multiplying both sides of equ. by

 $sin\left(\frac{2\pi nx}{L}\right)$  where *n* is an integer, and integrating around a latitude circle.

Applying the orthogonality relationships

$$\int_{0}^{L} \sin \frac{2\pi sx}{L} \sin \frac{2\pi nx}{L} dx = \begin{cases} 0 & s \neq n \\ L/2 & s = n \end{cases}$$
  
$$\therefore A_{s} = \frac{2}{L} \int_{0}^{L} f(x) \sin \frac{2\pi sx}{L} dx$$
  
In a similar fashion, multiplying both sides in equ. by  $\cos \left(\frac{2\pi nx}{L}\right)$  and integrating gives:  
$$B_{s} = \frac{2}{L} \int_{0}^{L} f(x) \cos \frac{2\pi sx}{L} dx$$
  
$$A_{s} \text{ and } B_{s} \text{ are called the Fourier coefficients}$$



#### **Dispersion and Group Velocity**

Wave groups formed from two sinusoidal components of slightly different wavelengths.





#### For nondispersive waves, propagates without change of shape

# **Non-Dispersive Waves**



- Some types of waves, such as acoustic waves, have phase speeds that are independent of the wave number.
- In such nondispersive waves a spatially localized disturbance consisting of a number of Fourier wave components (a wave group) will preserve its shape as it propagates in space at the phase speed of the wave.





## A Wave Solution Strategy

Approximations to the full equations governing atmospheric dynamics will be solved for wave motions many times.

Even though aspects of each individual case are different, a guide to the general approach to solving these problems isas follows:

- 1. Choose a basic state
  - 2. Linearize the governing equations
    - 3. Assume wave solutions of the form in equation  $f(x, y, t) = \operatorname{Re}(Ae^{i(kx+ly-\omega t)}) = \operatorname{Re}(Ae^{i\phi})$  $F_y e^{i(kx-\omega t)}$

4. Solve for the dispersion and polarization relationships

 $\wedge \downarrow \land$ 



Destructive Interference



# SIMPLE WAVE TYPES

- Waves in fluids result from the action of restoring forces on fluid parcels that have been displaced from their equilibrium positions.
- The restoring forces may be due to compressibility, gravity, rotation, or electromagnetic effects.
- This section considers the two simplest examples of linear waves in fluids:

1) acoustic waves

2) shallow water gravity waves



# Acoustic (Sound) Waves

1) Sound waves, or acoustic waves, are longitudinal waves

2) Sound is propagated by the alternating adiabatic compression and expansion of the medium.

As an example,









#### Describe mathematiclly

#### 1) the perturbation method

## 2) adiabatic

3) waves propagating in a straight pipe parallel to the x axis (one-dimensional sound)

4) To exclude the possibility of transverse oscillations (for simplicity) we assume:

$$\vec{V} = (u, 0, 0)$$
 and  $u = u(x, t)$ 

With these restrictions,

the momentum equation, thermodynamic energy equation continuity equation

for adiabatic motion are

$$\frac{du}{dt} + \frac{1}{\rho} \frac{\partial p}{\partial x} = 0$$
 momentum equation  

$$\frac{d\rho}{dt} + \rho \frac{\partial u}{\partial x} = 0$$
 continuity equation  

$$\frac{d \ln \theta}{dt} = 0$$
 thermodynamic energy equation  
For adiabatic process  

$$c_p \frac{dT}{dt} - \alpha \frac{dp}{dt} = \dot{q}$$
  
Dividing through by T and again using the equation of state, we obtain the  
entropy form of the first law of thermodynamics:

 $c_p \frac{d \ln T}{dt} - R \frac{d \ln p}{dt} = \frac{\dot{q}}{T} \equiv \frac{ds}{dt} \quad *$ 

the rate of change of entropy per unit mass following the thermodynamically reversible process.

$$\theta = T\left(\frac{p_0}{p}\right)^{R/c_p} \qquad c_p \frac{d \ln \theta}{dt} = c_p \frac{d \ln T}{dt} - R \frac{d \ln p}{dt}$$
Comparing \*, we ontain  $c_p \frac{d \ln \theta}{dt} = \frac{\dot{q}}{T} = \frac{ds}{dt}$ 
where for this case  $\frac{d}{dt} = \frac{\partial}{\partial t} - u \frac{\partial}{\partial x}$ 

$$\theta = \left(\frac{p}{\rho R}\right) \left(\frac{p_0}{p}\right)^{R/c_p} \rightarrow \ln \theta = \ln \frac{p_0^{\frac{R}{c_p}}}{R} + \ln p \frac{1-R}{c_p} - \ln \rho$$

$$\frac{d \ln \theta}{dt} = -\frac{d \ln \rho}{dt} + \frac{1}{\gamma} \frac{d \ln p}{dt} = 0 \qquad \text{where} \quad \frac{1-R}{c_p} = \frac{c_v}{c_p} = \frac{1}{\gamma}$$



where 
$$p_0 = 1000$$
 hPa, we may eliminate  $\theta$  in  $\frac{d \ln \theta}{dt} = 0$ 

$$\frac{1}{\gamma}\frac{d\ln p}{dt} - \frac{d\ln \rho}{dt} = 0 \qquad \qquad \frac{d\rho}{dt} + \rho\frac{\partial u}{\partial x} = 0$$

Eliminating p

$$\frac{1}{\gamma}\frac{d\ln p}{dt} + \frac{\partial u}{\partial x} = 0$$

The perturbation method

 $u(x,t) = \bar{u} + u'(x,t)$ 

 $p(x,t) = \bar{p} + p'(x,t)$ 

 $\rho(x,t) = \bar{\rho} + \rho'(x,t)$ 

Substituting into 
$$\frac{du}{dt} + \frac{1}{\rho} \frac{\partial p}{\partial x} = 0$$
 and  $\frac{1}{\gamma} \frac{d \ln p}{dt} + \frac{\partial u}{\partial x} = 0$ 

$$\frac{\partial}{\partial t}\left(\overline{u}+u'\right)+\left(\overline{u}+u'\right)\frac{\partial}{\partial x}\left(\overline{u}+u'\right)+\frac{1}{(\overline{\rho}+\rho')}\frac{\partial}{\partial x}\left(\overline{\rho}+p'\right)=0$$

$$\frac{\partial}{\partial t}\left(\overline{p}+p'\right)+\left(\overline{u}+u'\right)\frac{\partial}{\partial x}\left(\overline{p}+p'\right)+\gamma\left(\overline{p}+p'\right)\frac{\partial}{\partial x}\left(\overline{u}+u'\right)=0$$

 $|\rho'|\overline{\rho}| \ll 1$  we can use the binomial expansion to approximate the density term as

$$\frac{1}{(\overline{\rho}+\rho')} = \frac{1}{\overline{\rho}} \left(1+\frac{\rho'}{\overline{\rho}}\right)^{-1} \approx \frac{1}{\overline{\rho}} \left(1-\frac{\rho'}{\overline{\rho}}\right)$$

we obtain the linear perturbation equations

$$\left(\frac{\partial}{\partial t} + \bar{u}\frac{\partial}{\partial x}\right)u' + \frac{1}{\bar{\rho}}\frac{\partial p'}{\partial x} = 0 \qquad \left(\frac{\partial}{\partial t} + \bar{u}\frac{\partial}{\partial x}\right)p' + \gamma\bar{p}\frac{\partial u'}{\partial x} = 0$$

Eliminate *u'* by applying 
$$\left(\frac{\partial}{\partial t} + \overline{u}\frac{\partial}{\partial x}\right)$$
 on \*  
 $\frac{\partial}{\partial t} + \overline{u}\frac{\partial}{\partial x}u' = -\frac{1}{\overline{\rho}}\frac{\partial p'}{\partial x}$   
 $\frac{\partial}{\partial t} + \overline{u}\frac{\partial}{\partial x}p' + \gamma \overline{p}\frac{\partial u'}{\partial x} = 0$  \*  
 $\frac{\partial}{\partial t} + \overline{u}\frac{\partial}{\partial x}u' = -\frac{\gamma \overline{p}}{\overline{\rho}}\frac{\partial^2 p'}{\partial x^2} = 0$ 

which is a form of the standard wave equation familiar from electromagnetic theory. A simple solution representing a plane sinusoidal wave propagating in x is

$$p' = A e^{ik(x-ct)}$$

the assumed solution

$$\begin{split} \left(\frac{\partial}{\partial t} + \bar{u}\frac{\partial}{\partial x}\right)^2 p' &- \frac{\gamma \bar{p}}{\bar{\rho}}\frac{\partial^2 p'}{\partial x^2} = 0 \qquad p' = A e^{ik(x-ct)} \\ \left(\frac{\partial}{\partial t} + \bar{u}\frac{\partial}{\partial x}\right)^2 p' &= \left(\frac{\partial^2}{\partial t^2} + 2\bar{u}\frac{\partial^2}{\partial x\partial t} + \bar{u}^2\frac{\partial^2}{\partial x^2}\right)p' = (-ikc + ik\bar{u})^2p' \\ \frac{\gamma \bar{p}}{\bar{\rho}}\frac{\partial^2 p'}{\partial x^2} &= \frac{\gamma \bar{p}}{\bar{\rho}}(ik)^2p' \\ (-ikc + ik\bar{u})^2 - \frac{\gamma \bar{p}}{\bar{\rho}}(ik)^2 = 0 \qquad \text{Dispersion relation} \\ \text{Solving for c gives} \\ c &= \bar{u} + \sqrt{\frac{\gamma \bar{p}}{\bar{\rho}}} = \bar{u} + \sqrt{\gamma R \bar{T}} \qquad \text{the phase speed} \end{split}$$



the speed of wave propagation relative to the zonal current is

where  $c_s = \sqrt{\gamma R \bar{T}}$  is called the adiabatic speed of sound

The mean zonal velocity here plays only a role of Doppler shifting the sound wave so that the frequency relative to the ground corresponding to a given wave number k is:

$$\omega = kc = k(\bar{u} \pm c_s)$$

 $c - \bar{u} = \pm c_s$ 

Thus, in the presence of a wind, the frequency as heard by a fixed observer depends on the location of the observer relative to the source.

## if $\bar{u} > 0$

The frequency of a stationary source will appear to be higher for an observer to the east (downstream) of the source

 $c = \bar{u} + c_s$ 

than for an observer to the west (upstream) of the source

 $c=\bar{u}-c_s$